Correlation and Lead-Lag Relationships in a Hawkes Microstructure Model

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Abstract

The aim of this paper is to develop a multi-asset model based on the Hawkes process describing the evolution of the assets at high frequency and to study the lead-lag relationship as well as the correlation between the stocks within this framework. Thanks to its strong analytical tractability several statistical quantities are explicitly computed and give some insight on the impact of the model parameters on these quantities. Furthermore, we compute the covariance matrix associated with the diffusive limit of the model so that the relation between the parameters driving the asset at high and low frequencies is explicit. We illustrate our results using index futures and stocks quoted in the Eurex market. The model can capture the existing lead-lag relationship between the assets.

JEL Classification: C13, C32, C58.

Keywords: Hawkes process, Lead-Lag relationship, Correlation, Diffusive limit, High Frequency.

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1 Introduction

The interaction between stocks is an important aspect of financial theory. From optimal portfolio choice to basket option pricing one of the key ingredient is the modelling of the dependency between stocks. The correlation appears to be the natural mathematical concept to handle the interaction and in fact underlies many financial models. The correlation provides information on contemporaneous evolutions but in the markets this simultaneousness can be too stringent. A concept that relaxes this hypothesis is the lead-lag relationship which has also been extensively studied in the literature, among many others let us mention [Herbst et al. (1987)]. More recently, the availability of high-frequency data also triggered research on this subject as the works of [de Jong and Nijman (1997)] and [Huth and Abergel (2012)] attest.

The purpose of this work is to develop a multi-asset model for stocks based on the Hawkes process and to study the correlation and lead-lag relationship within this framework. The model specifies the high-frequency dynamic for the stocks and heavily relies on the single-stock dynamic model proposed by [Bacry et al. (2013a)] and further extended to the multi-asset case in [Bacry et al. (2013b)]. In the particular case of exponential kernel for the Hawkes process, initially proposed by [Hawkes (1971)] which allows for very explicit computations, we develop a model for which many of the statistical properties of the stocks can be computed. The model displays clustering and/or mean reversion behaviour for the stock volatilities as in [Da Fonseca and Zaatour (2013b)]. Using the theoretical results of [Bacry et al. (2013b)] we compute the diffusive limit for the stocks thereby connecting the model driving the assets at high frequency with the covariance matrix driving the assets at low frequency (i.e., daily). Within this framework we analyse the correlation as well as the lead-lag relationship between the stocks and provide some expansions to better understand the impact of the model parameters on different financial quantities. We then perform an empirical analysis on two index futures and four major stocks quoted on the Eurex market to illustrate the model. As expected, we find that the major index futures leads all the other assets (either stocks or “smaller” index futures). Between two similar assets (i.e., two stocks) the lead-lag relationship is time varying and when averaged over a long period no stock systematically leads the others. In a very particular case where one of the stock leads the other

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1For other financial applications of the Hawkes process see for example Branger et al. (2013), Gagliardini and Gouriéroux (2013).

2The problem of connecting the dynamics for the stocks at different time scales appears recently in several works. Without being exhaustive let us mention Cont and De Larrard (2012), Bacry et al. (2013a), Bacry et al. (2013b), Abergel and Jedidi (2013a), Abergel and Jedidi (2013b), Kirilenko et al. (2013).
the shareholder structure provides a reasonable explanation. Lastly, within our framework extracting lead-lag relationship between stocks at low frequency is problematic and confirms the results of Huth and Abergel (2012).

The structure of the paper is as follows. In the first section, we describe the analytical framework which comprises the basic properties of the Hawkes process as well as the Dynkin formula that allows the computation of the moments and the autocorrelation function of the number of jumps over a given time interval. In the second section, given a dynamic for two stocks based on the Hawkes process we derive various statistical quantities as well as the expression for the diffusive limit associated with the two stocks. In the third section, an empirical analysis is performed to illustrate the capabilities of the model. Finally, we conclude and some technical results, tables and figures which are gathered in the appendix.

2 Mathematical Framework

2.1 The multivariate Hawkes process

Let $X_t = (\lambda_t, N_t)$ is a Markov process in the state space $D = \mathbb{R}_+^n \times \mathbb{N}^n$, which satisfies the dynamic:

$$d\lambda_t = \beta(\lambda_\infty - \lambda_t)dt + \alpha dN_t$$

with $\beta$, $\alpha$ two $n \times n$ real matrices and $\lambda_\infty$ a vector of $\mathbb{R}^n$. Applying Ito’s lemma to $e^{\beta t} \lambda_t$ yields:

$$\lambda_t = e^{-\beta t} (\lambda_0 - \lambda_\infty) + \lambda_\infty + \int_0^t e^{-\beta (t-v)} \alpha dN_v.$$  

From (2) and under the hypothesis that $\beta$ has positive eigenvalues we observe that the impact on the intensity of a jump dies out exponentially as time passes. Also, as the intensities must be positive we deduce that the matrix $\alpha$ has to be component-wise positive. For the existence and uniqueness results we refer to Chapter 14 of Daley and Jones (2008) and references therein, of particular interest is Brémaud and Massoulié (1994).

As $t$ gets larger the impact of $\lambda_0$, the initial value for the intensity, vanishes leaving us with:

$$\lambda_t \sim \lambda_\infty + \int_0^t e^{-\beta (t-v)} \alpha dN_v.$$
Our presentation differs slightly from the usual one found in the literature where the Hawkes intensity is written as:

\[ \lambda_t = \lambda_\infty + \int_{-\infty}^{t} e^{-\beta(t-v)} \alpha dN_v. \]  

(3)

The equation (3) leads to a stochastic differential equation similar to (1), the process starts infinitely in the past and is at its stationary regime. In our case we have a dependency with respect to the initial position \( \lambda_0 \) in equation (2) but, as mentioned above, as \( t \) gets larger its impact vanishes.

Our presentation for the Hawkes process follows closely Errais et al. (2010) and is motivated by the fact that we want to perform stochastic differential calculus.

The infinitesimal generator of the diffusion is given by

\[ \mathcal{L} f = (\beta(\lambda_\infty - \lambda))^\top \nabla^\top f + \lambda^\top \begin{pmatrix} f(\lambda + \alpha e_1, N_t + e_1) - f \\ \vdots \\ f(\lambda + \alpha e_n, N_t + e_n) - f \end{pmatrix} \]  

(4)

for \( f : D \to \mathbb{R} \), where \( \nabla f = (\partial_{\lambda_1} f, ..., \partial_{\lambda_n} f) \) is a 1 \( \times \) n vector and \((e_i)_{i=1..n}\) is the canonical basis of \( \mathbb{R}^n \) (\( ^\top \) stands for the matrix transpose). For every function \( f \) in the domain of the infinitesimal generator, the process:

\[ M_t = f(X_t) - f(X_0) - \int_0^t \mathcal{L} f(X_v) \, dv \]

is a martingale relative to its natural filtration (see for example Proposition 1.6 of chapter VII in Revuz and Yor (1999)) and for \( s > t \) we have:

\[ \mathbb{E} \left[ f(X_s) - \int_0^s \mathcal{L} f(X_v) \, dv \mid \mathcal{F}_t \right] = f(X_t) + \int_t^s \mathcal{L} f(v, X_v) \, dv \]

by the martingale property, so finally:

\[ \mathbb{E} \left[ f(X_s) \mid \mathcal{F}_t \right] = f(X_t) + \mathbb{E} \left[ \int_t^s \mathcal{L} f(X_v) \, dv \mid \mathcal{F}_t \right]. \]  

(5)

This gives a very convenient way to calculate conditional expectations of functions of the Markov process \( X_t = (\lambda_t, N_t) \) when the expectation of the right hand side of the preceding equation can be easily computed.
Notice also that taking the expectation of the above formula turns the conditional expectation into an unconditional expectation of quantities depending on the process \((\lambda_t, N_t)\).

The infinitesimal generator of the diffusion leads, thanks to Feynman-Kac’s formula, to the computation of the moment-generating function. Denoted by \(\phi(t, z, u) = \mathbb{E}\left[ e^{z^\top \lambda_t + u^\top N_t} \right]\) for \(z \in \mathbb{R}^n\) and \(u \in \mathbb{N}^n\), this function solves the partial differential equation with initial condition:

\[
\begin{cases}
\partial_t \phi = \mathcal{L} \phi \\
\phi(0, z, u) = e^{z^\top \lambda_0 + u^\top N_0}.
\end{cases}
\]

The model being affine we look for a solution of the form \(e^{a_t + b_t^\top \lambda + u^\top N}\) with \(a_t \in \mathbb{R}\) and \(b_t \in \mathbb{R}^n\). It leads to a set of ordinary differential equations:

\[
\begin{cases}
\partial_t a = b^\top \beta \lambda_{\infty} \\
\partial_t b = -\beta^\top b + h - 1
\end{cases}
\]

with initial conditions \(a_0 = 0, b_0 = z\), and \(1 = (1, \ldots, 1)^\top\) whilst the function \(h\) is defined as:

\[
h = \begin{pmatrix}
e^{b^\top \alpha e_1 + u^\top e_1} \\
\vdots \\
e^{b^\top \alpha e_n + u^\top e_n}.
\end{pmatrix}
\]

From a numerical point of view it is always possible to simulate the ODE but explicitly computing the solution is difficult. Also, if we are interested in the moments of the process then we need to derive the solution with respect to the parameter \(z\) which in turn leads to the computation of the derivative with respect to this parameter of the ODE. Although the first moment can be easily computed, higher moments remain a challenge. To the extent that we are interested only in the moments we can devise a simpler computation strategy based on Dynkin’s formula (5).

### 2.2 The moments and autocorrelation function

We report in these section the expression for the moments of the process \(X_t = (\lambda_t, N_t)\) and also the autocovariance of the number of jumps over a period \(\tau\). These results heavily rely on the use of the infinitesimal generator of the process given by (4) and Dynkin’s formula (5). To make the document self-contained we report in the appendix for the following results a sketch of the proofs (see also Da Fonseca and Zaatour (2013a) and Da Fonseca and Zaatour (2013b)). We refer to Errais et al.
Lemma 1. Given a Hawkes process $X_t = (\lambda_t, N_t)$ with dynamic given by (1) then the expected number of jumps $\mathbb{E}[N_t]$ and the expected intensity $\mathbb{E}[\lambda_t]$ satisfy the set of ODE:

$$d\mathbb{E}[\lambda_t] = \beta(\lambda_\infty - \mathbb{E}[\lambda_t])dt + \alpha\mathbb{E}[\lambda_t]dt,$$

$$d\mathbb{E}[N_t] = \mathbb{E}[\lambda_t]dt.$$ 

These equations can be integrated explicitly as we have:

$$\mathbb{E}[\lambda_t] = (\alpha - \beta)^{-1} \left( e^{(\alpha-\beta)t} - I \right) \beta \lambda_\infty + e^{(\alpha-\beta)t} \lambda_0$$

$$= c_0(t)\lambda_0 + c_1(t)$$

and

$$\mathbb{E}[N_t] = N_0 + (\alpha - \beta)^{-1} \left( e^{(\alpha-\beta)t} - I \right) \lambda_0 + \left( ((\alpha - \beta)^{-1})^2 \left( e^{(\alpha-\beta)t} - I \right) \beta \lambda_\infty - (\alpha - \beta)^{-1} \beta \lambda_\infty t \right)$$

$$= N_0 + c_2(t)\lambda_0 + c_3(t).$$

Thanks to these two solutions we can compute the following asymptotic expectations:

Lemma 2. Given a Hawkes process with dynamic given by (1) then long term expected intensity is given by:

$$\lim_{t \to +\infty} \mathbb{E}[\lambda_t] = \bar{\lambda}_\infty = -(\alpha - \beta)^{-1} \beta \lambda_\infty$$

whereas the long term expected number of jumps over an interval $\tau$ is:

$$\lim_{t \to +\infty} \mathbb{E}[N_{t+\tau} - N_t] = -(\alpha - \beta)^{-1} \beta \lambda_\infty \tau$$

Establishing (11) requires that $\alpha - \beta$ has negative eigenvalues, which is the classical stability condition of the multivariate Hawkes Process as stated in Hawkes (1971). Therefore, from now on we will suppose this property satisfied. We are interested in asymptotic values because in the applications developed in this paper the variable $N_t$ will be observable but not the intensity $\lambda_t$. As a result, any
time \( t \) conditional expectation of the process \( N_{t+\tau} \) will depend, a priori, on \( \lambda_t \) and to simplify this dependency with respect to this unobservable variable we set the process to its long term value (by taking the limit for \( t \to +\infty \)). This astute strategy, used in Bacry et al. (2013a) or Aït-Sahalia et al. (2010), eases significantly the applications. The computation of the second order moments leads to the following lemma:

**Lemma 3** Given a Hawkes process \( X_t = (\lambda_t, N_t) \) with dynamic given by \([1]\) then the functions

\[
E[N_t N_t^\top], \ E[\lambda_t N_t^\top] \quad \text{and} \quad E[\lambda_t \lambda_t^\top]
\]

solve the set of ODE:

\[
\begin{align*}
\frac{d}{dt} E[N_t N_t^\top] &= E[\lambda_t N_t^\top] + E[N_t \lambda_t^\top] + \text{diag}(E[\lambda_t]),\tag{14}
\frac{d}{dt} E[\lambda_t N_t^\top] &= \beta \lambda_\infty E[N_t^\top] + (\alpha - \beta) E[\lambda_t N_t^\top] + E[\lambda_t \lambda_t^\top] + \alpha \text{diag}(E[\lambda_t]),\tag{15}
\frac{d}{dt} E[\lambda_t \lambda_t^\top] &= \beta \lambda_\infty E[\lambda_t^\top] + E[\lambda_t] \lambda_\infty^\top \beta^\top + (\alpha - \beta) E[\lambda_t \lambda_t^\top] + E[\lambda_t \lambda_t^\top] (\alpha - \beta)^\top + \alpha \text{diag}(E[\lambda_t]) \alpha^\top \tag{16}
\end{align*}
\]

and the long term covariance matrix for the intensity \( \Lambda_\infty = \lim_{t \to +\infty} E[\lambda_t \lambda_t^\top] \) solves the algebraic matrix equation:

\[
(\alpha - \beta) \bar{\Lambda}_\infty + \bar{\Lambda}_\infty (\alpha - \beta)^\top + \alpha \text{diag}(\bar{\lambda}_\infty) \alpha^\top = 0 \quad \text{(17)}
\]

with \( \bar{\Lambda}_\infty = \Lambda_\infty - \bar{\lambda}_\infty \bar{\lambda}_\infty^\top \) where \( \bar{\lambda}_\infty \) is given by \([11]\).

Using the previous lemmas we can compute second order moment as well as the auto-covariance function of the number of jumps over a given time interval as we have:

**Lemma 4** The long term second order moment of the number of jumps over a given interval \( \tau > 0 \) is:

\[
\begin{align*}
\text{Cov}(\tau) &= \lim_{t \to +\infty} E[(N_{t+\tau} - N_t)(N_{t+\tau} - N_t)^\top] - E[(N_{t+\tau} - N_t)] E[(N_{t+\tau} - N_t)^\top]
\quad = J_1 + J_1^\top + \tau \text{diag}(\bar{\lambda}_\infty) \tag{18}
\end{align*}
\]

with \( J_1 = c_5(\tau)(\bar{\Lambda}_\infty + \alpha \text{diag}(\bar{\lambda}_\infty)) \) and

\[
c_5(\tau) = - (\alpha - \beta)^{-1} \tau + (\alpha - \beta)^{-2} (e^{(\alpha-\beta)\tau} - I). \quad \text{(19)}
\]

As we are interested in the autocorrelation structure of the process the following quantity proves to be essential:
Lemma 5 Given $t_1 < t_2 \leq t_3 < t_4$ with $t_2 - t_1 = \tau_1$, $t_4 - t_3 = \tau_2$ and $t_3 - t_2 = \delta$ we have:

\[
\text{Cov}_1(\tau_1, \tau_2, \delta) = \lim_{t_1 \to +\infty} \mathbb{E}\left[ (N_{t_4} - N_{t_3})(N_{t_2} - N_{t_1})^\top \right] - \mathbb{E}[N_{t_4} - N_{t_3}] \mathbb{E}\left[ (N_{t_2} - N_{t_1})^\top \right]
= c_2(\tau_2)c_0(\delta)c_2(\tau_1) (\bar{\Lambda}_\infty + \alpha \text{diag}(\bar{\lambda}_\infty))
\tag{20}
\]

with $\bar{\Lambda}_\infty$ given by \eqref{17} and $\bar{\lambda}_\infty$ by \eqref{11}.

It is possible to relax the assumption of overlapping intervals made in the previous lemma. In fact, we have:

Lemma 6 Given $t_1 < t_3 \leq t_2 < t_4$ with $t_2 - t_1 = \tau_1$, $t_4 - t_3 = \tau_2$ and $t_3 - t_1 = \delta$ (note the difference with the previous lemma), then:

\[
\text{Cov}_2(\tau_1, \tau_2, \delta) = \lim_{t_1 \to +\infty} \mathbb{E}\left[ (N_{t_4} - N_{t_3})(N_{t_2} - N_{t_1})^\top \right] - \mathbb{E}[N_{t_4} - N_{t_3}] \mathbb{E}\left[ (N_{t_2} - N_{t_1})^\top \right]
= \text{Cov}_1(\tau_1, \tau_2 - (\tau_1 - \delta), 0) + \text{Cov}(\tau_1 - \delta) + \text{Cov}_1(\delta, \tau_1 - \delta, 0).
\tag{21}
\]

The expression for the autocovariance function leads naturally to the autocorrelation function of the number of jumps over a given time interval denoted as $\text{CORR}(\tau, \delta)$ which is a function of:

\[
\lim_{t \to +\infty} \mathbb{E}\left[ (N_{t+\tau} - N_t)(N_{t+\tau+\delta} - N_{t+\delta})^\top \right] - \mathbb{E}[N_{t+\tau} - N_t] \mathbb{E}\left[ (N_{t+\tau+\delta} - N_{t+\delta})^\top \right]
\tag{22}
\]

where, depending whether $\delta \geq \tau$ or not, we use either \eqref{20} or \eqref{21} and the square root of the diagonal terms of the matrices $\text{Cov}(\tau)$. The lemma 5 leads to the following useful result whose proof is straightforward

Lemma 7 Given the covariance matrix $\text{Cov}_1(\tau_1, \tau_2, \delta)$ defined by \eqref{20} then we have:

\[
\bar{\Sigma} = \sum_{j=0}^{\infty} \text{Cov}_1(1, 1, j)
= (\alpha - \beta)^{-2}(I - e^{(\alpha-\beta)}(\bar{\Lambda}_\infty + \alpha \text{diag}(\bar{\lambda}_\infty)).
\tag{23}
\]

A last lemma which eases significantly the computation is given by:

Lemma 8 We suppose a four-dimensional Hawkes process $X_t = (\lambda_t, N_t)$ with values in $D = \mathbb{R}_+^4 \times \mathbb{N}_4$.

Given the matrix $\bar{\Sigma}$ of \eqref{18}, the covariance matrix $\text{Cov}(1)$ defined by \eqref{18} and define $M = \text{Cov}(1) + 2\bar{\Sigma}$ then:

\[
M_{11} + M_{22} - M_{12} - M_{21} = \bar{M}_{11} + \bar{M}_{22} - \bar{M}_{12} - \bar{M}_{21},
\tag{24}
\]

\[
M_{33} + M_{44} - M_{34} - M_{43} = \bar{M}_{33} + \bar{M}_{44} - \bar{M}_{34} - \bar{M}_{43}
\tag{25}
\]
with:

\[ \tilde{M} = \tilde{J}_1 + \tilde{J}_1^\top + \text{diag}(\bar{\lambda}_\infty), \quad (26) \]
\[ \tilde{J}_1 = - (\alpha - \beta)^{-1} (\bar{\Lambda}_\infty + \text{adiag}(\bar{\lambda}_\infty)). \quad (27) \]

The numerical consequences of the previous lemma are important because the left hand side of (24)
(or (25)) involves exponential of matrices, through \( c_5 \) of Lemma 4, whereas the right hand side involves
no exponentiation.

These lemmas provide the main equations that will be involved in the applications developed in this
paper.

3 The Bacry-Delattre-Hoffmann-Muzy Model

3.1 The stock dynamics

We adopt the modelling framework proposed by (Bacry et al., 2013a) to describe the evolution of the
mid price of two traded assets:

\[ S_1^t = S_0^1 + \left( N_{1, u}^t - N_{1, d}^t \right) \frac{\nu_1}{2}, \]
\[ S_2^t = S_0^2 + \left( N_{2, u}^t - N_{2, d}^t \right) \frac{\nu_2}{2}, \]

where \(\nu_1\) and \(\nu_2\) are the tick values for the first stock and second stock, respectively. Let, \( N_{1, u}^t \) and \( N_{1, d}^t \) be Hawkes processes capturing the up and down jumps of the mid price for the first stock and \( N_{2, u}^t \) and \( N_{2, d}^t \) the corresponding equivalent for the second stock.

In this work the four dimensional Hawkes process \( N_t = (N_{1, u}^t, N_{1, d}^t, N_{2, u}^t, N_{2, d}^t)^\top \) and \( \lambda_t = (\lambda_{1, u}^t, \lambda_{1, d}^t, \lambda_{2, u}^t, \lambda_{2, d}^t)^\top \) follow a dynamic of the form (1) with:

\[ \alpha = \begin{pmatrix} \alpha_s^1 & \alpha_m^1 & x & 0 \\ \alpha_m^1 & \alpha_s^1 & 0 & x \\ y & 0 & \alpha_s^2 & \alpha_m^2 \\ 0 & y & \alpha_m^2 & \alpha_s^2 \end{pmatrix}; \quad \beta = \begin{pmatrix} \bar{\beta}_1 & 0 & 0 & 0 \\ 0 & \bar{\beta}_1 & 0 & 0 \\ 0 & 0 & \bar{\beta}_2 & 0 \\ 0 & 0 & 0 & \bar{\beta}_2 \end{pmatrix} \quad (28) \]

and \( \lambda_\infty = (\lambda_{1, \infty}, \lambda_{1, \infty}, \lambda_{2, \infty}, \lambda_{2, \infty})^\top \in \mathbb{R}_+^4 \).
The connection between the two stocks is controlled through the $2 \times 2$ upper-right and lower-left sub-matrices (called coupling submatrices in the sequel). Here, we supposed that the two stocks have an overall positive correlation, hence our parametrization. Notice that if $x = y = 0$ then the two stocks move independently.

As $x > 0$, an up move of the second stock, through a jump of $N_{2,u}^{2,t}$, induces an increase of the intensity $\lambda_{1,u}$ which increases the probability of a jump of $N_{1,u}^{1,t}$ over the next time period and therefore an up move of the first stock. Similar reasoning applies to a down move. As a consequence, the movements of the second stock will be reproduced by the first stock. By construction these related evolutions are not simultaneous, and will lead to lead lag relationship when observed at the adequate time scale. In the specific case where $x > 0$ and $y = 0$, the second asset leads the first asset and we can qualify as a positive lead-lag relationship, as the stocks will move in the same direction and that their overall correlation will be positive.

We restrict ourselves to a very particular form for the coupling submatrices matrices in order to make as much as possible explicit the dependency between the stocks. For example, the $2 \times 2$ upper-right matrix of $\alpha$ could be replaced with:

$$
\begin{pmatrix}
  x_1 & 0 \\
  0 & x_2
\end{pmatrix},
$$

then the impact of an up move of the second stock on the first one will be different from the impact of a down move (of the second asset on the first asset). A priori this is an appealing feature because linkages between stocks are indeed different in bear and bull markets. However, to keep the analytical expressions simple we restrict this study to the symmetric model (i.e., $x_1 = x_2$).

If we wish to consider negative lead-lag relationship of the second stock on the first one, that is to say a resulting negative correlation, then the $2 \times 2$ upper-right sub-matrix of $\alpha$ should be:

$$
\begin{pmatrix}
  0 & x \\
  x & 0
\end{pmatrix},
$$

also with the possibility to differentiate up and down moves.

Similar considerations apply to $2 \times 2$ lower-left sub-matrix of $\alpha$ that controls the transmission of the
shocks affecting the first stock to the second stock. Also, it is worth underlining the possibility of
disymmetric effects between the two stocks in the sense that the impact of the first stock on the
second one need not to be equal to, nor in the same direction, of the impact of the second stock on the
first one. This strongly contrasts with the usual correlation which by definition is a reflexive relation.
Although the model allows for a disymmetric relationship between the stocks it seems to us natural
to choose the upper-right matrix consistently with the lower-left matrix. For the choice made for the
$2 \times 2$ upper-right matrix of $\alpha$ in (28) the natural choice is the one made for the lower-left sub-matrix
whereas in the case of (30) then the natural choice is:
\[
\begin{pmatrix}
0 & y \\
y & 0
\end{pmatrix}.
\] (31)
It would be even tempting to choose $x = y$ so that the lead-lag relationship would be reflexive. How-
ever, there are some practical cases where allowing for some disymmetry, that is to say different values
for $x$ and $y$, is particularly relevant; the most well-known example being the relation between a futures
on an index and a stock.

Following (Bacry et al., 2013a) we will be interested in the diffusive limit for $S_t = (S_{1t}, S_{2t})^\top$ associated
with the dynamics (28). In order to perform such a limit computation the matrices $\alpha$ and $\beta$ in (28)
are such that $\mathbb{E}[N_{1t},u_t] = \mathbb{E}[N_{1t},d_t] = \mathbb{E}[N_{2t},u_t] = \mathbb{E}[N_{2t},d_t]$, this ensures the martingale property for the
stocks. This martingale property can be obtained for more general matrices $\alpha$ and $\beta$ but we restrict
this study these particular forms to keep the expressions simple.

Thanks to the computations made above we know that the matrix $\alpha - \beta$ must have negative eigenvalues
for the multivariate Hawkes process to be stable, which translates to:
\[
\begin{align*}
\gamma_1 + \gamma_2 & \pm \left( (\gamma_1 + \gamma_2)^2 - 4(\gamma_1 \gamma_2 - xy) \right)^{\frac{1}{2}} > 0, \\
\theta_1 + \theta_2 & \pm \left( (\theta_1 + \theta_2)^2 - 4(\theta_1 \theta_2 - xy) \right)^{\frac{1}{2}} > 0
\end{align*}
\] (32) (33)
with $\gamma_i = \beta_i + \alpha_{i}^{m} - \alpha_{i}^{s}$, $\theta_i = \beta_i - \alpha_{i}^{m} - \alpha_{i}^{s}$ for $i \in \{1, 2\}$. Conditions ensuring these inequalities are
$\gamma_1 \gamma_2 > xy$ and $\theta_1 \theta_2 > xy$ that, from now on, we suppose satisfied.

3.2 Statistical properties

Having specified the dynamics for the stocks we focus on the computation of various statistical proper-
ties associated with the assets. The use of high-frequency data enables the computation of the realized
volatility and the estimator, for data sampled using time intervals of length \( \tau \), is written as:

\[
C_1(\tau) = \frac{1}{T} \sum_{n=0}^{T/\tau-1} (S_{(n+1)\tau}^1 - S_{n\tau}^1)^2 = \frac{1}{T} \sum_{n=0}^{T/\tau-1} \left( N_{(n+1)\tau}^{1,u} - N_{n\tau}^{1,u} \right) - \left( N_{(n+1)\tau}^{1,d} - N_{n\tau}^{1,d} \right) \right)^2 \frac{\nu^2}{4} 
\]

\[
= \frac{1}{T} \sum_{n=0}^{T/\tau-1} \left( N_{(n+1)\tau}^{1,u} - N_{n\tau}^{1,u} \right)^2 \frac{\nu^2}{4} + \frac{1}{T} \sum_{n=0}^{T/\tau-1} \left( N_{(n+1)\tau}^{1,d} - N_{n\tau}^{1,d} \right)^2 \frac{\nu^2}{4} 
\]

\[
- 2 \frac{1}{T} \sum_{n=0}^{T/\tau-1} \left( N_{(n+1)\tau}^{1,u} - N_{n\tau}^{1,u} \right) \left( N_{(n+1)\tau}^{1,d} - N_{n\tau}^{1,d} \right) \frac{\nu^2}{4}
\]

The mean signature plot, or more simply signature plot, is the expectation of the above quantity and is explicitly given by:

**Proposition 9** The signature plot for the first asset \( C_1(\tau) = \mathbb{E}[\tilde{C}_1(\tau)] \) is:

\[
C_1(\tau) = \frac{\nu^2}{4\tau} \left( M_{11} + M_{22} - M_{12} - M_{21} \right)
\]  

(34)

where \( M = \text{ Cov}(\tau) \) is the second moment matrix calculated in Lemma 4.

The volatility of the second stock is obtained by the same calculations:

\[
C_2(\tau) = \frac{\nu^2}{4\tau} \left( M_{33} + M_{44} - M_{34} - M_{43} \right)
\]  

(35)

This expression appears in Da Fonseca and Zaatour (2013a) and Da Fonseca and Zaatour (2013b) in the single-stock model and for specific values for the parameters it leads to an expression already available in Bacry et al. (2013a). Nevertheless, it remains interesting to calculate it within the multi-asset model proposed here. For instance, let \( S_t^1 \) be a stock and \( S_t^2 \) be an index future that captures the overall market evolution. We can then assess the part of stock volatility that can be explained by market activity through the coupling parameters \( x \) and \( y \). We will make this more clear in the sequel.

As we deal with a multi-asset model, the covariance between the two stocks is the quantity of interest and can be obtained by the usual estimator:

\[
\text{CovS}(\tau) = \frac{1}{T} \sum_{n=0}^{T/\tau-1} \left( S_{(n+1)\tau}^1 - S_{n\tau}^1 \right) \left( S_{(n+1)\tau}^2 - S_{n\tau}^2 \right)
\]

\[
= \frac{1}{T} \sum_{n=0}^{T/\tau-1} \left[ \left( N_{(n+1)\tau}^{1,u} - N_{n\tau}^{1,u} \right) \left( N_{(n+1)\tau}^{2,u} - N_{n\tau}^{2,u} \right) - \left( N_{(n+1)\tau}^{1,d} - N_{n\tau}^{1,d} \right) \left( N_{(n+1)\tau}^{2,d} - N_{n\tau}^{2,d} \right) \right] \frac{\nu^2}{4}
\]

\[
- \left( N_{(n+1)\tau}^{1,d} - N_{n\tau}^{1,d} \right) \left( N_{(n+1)\tau}^{2,u} - N_{n\tau}^{2,u} \right) + \left( N_{(n+1)\tau}^{1,u} - N_{n\tau}^{1,u} \right) \left( N_{(n+1)\tau}^{2,d} - N_{n\tau}^{2,d} \right) \frac{\nu^2}{4}
\]

This estimator along with the analytical results, mainly the second moment of Lemma 4, lead to an explicit expression for the covariance as the following proposition shows:
Proposition 10 The covariance between the two stocks implied by $\hat{\text{Cov}}S(\tau)$ is:

$$\text{CovS}(\tau) = \frac{\nu_1\nu_2}{4\tau} \left[ M_{13} - M_{14} - M_{23} + M_{24} \right] = \frac{\nu_1\nu_2}{4\tau} \left[ M_{31} - M_{41} - M_{32} + M_{42} \right]$$

with the matrix $M = \text{COV}(\tau)$ given by (18) of Lemma 4. The last equality in (36) stands from the symmetry of the matrix $M$.

Rescaling by the above calculated volatilities of the stocks, one obtains an estimator of the correlation as a function of the sampling period $\tau$, and retrieves the well known Epps effect. Recall that this effect materializes in the decrease of the estimated correlation when the sampling frequency increases. An illustration in this model is given in Figure 1.

Beyond the correlation between the two stocks is the lead-lag relationship. The estimator of the lagged covariance between the two stocks if we consider $S^2$ as the leader is:

$$\hat{L}_{2 \rightarrow 1}(\tau, \delta) = \frac{1}{T} \sum_{n=0}^{T/\tau - 1} (S^1_{(n+1)\tau + \delta} - S^1_{n\tau + \delta}) \left( S^2_{(n+1)\tau} - S^2_{n\tau} \right)$$

$$= \frac{1}{T} \sum_{n=0}^{T/\tau - 1} \left[ (N^1_{(n+1)\tau + \delta} - N^1_{n\tau + \delta}) (N^2_{(n+1)\tau} - N^2_{n\tau}) - (N^1_{(n+1)\tau + \delta} - N^1_{n\tau + \delta}) (N^2_{(n+1)\tau} - N^2_{n\tau}) \right]$$

$$\nu_1\nu_2 \frac{4}{\tau}.$$

for $\delta > 0$. Conversely, if the first stock is taken as the leader the estimator becomes:

$$\hat{L}_{1 \rightarrow 2}(\tau, \delta) = \frac{1}{T} \sum_{n=0}^{T/\tau - 1} (S^2_{(n+1)\tau + \delta} - S^2_{n\tau + \delta}) \left( S^1_{(n+1)\tau} - S^1_{n\tau} \right).$$

These two estimators combined with the results developed in the analytical part give the following proposition:

Proposition 11 Given the two estimators defined above then the estimated lagged covariances, depending on which asset is chosen as leader, write as:

$$L_{2 \rightarrow 1}(\tau, \delta) = \frac{\nu_1\nu_2}{4\tau} \left[ \text{Cov}C(\tau, \delta)_{13} - \text{Cov}C(\tau, \delta)_{14} - \text{Cov}C(\tau, \delta)_{23} + \text{Cov}C(\tau, \delta)_{24} \right]$$

$$L_{1 \rightarrow 2}(\tau, \delta) = \frac{\nu_1\nu_2}{4\tau} \left[ \text{Cov}C(\tau, \delta)_{31} - \text{Cov}C(\tau, \delta)_{32} - \text{Cov}C(\tau, \delta)_{41} + \text{Cov}C(\tau, \delta)_{42} \right].$$
for $\tau > 0$ and $\delta > 0$ whilst $\text{Cov}(\tau, \delta)$ stands for $\text{Cov}_1(\tau, \tau, \delta)$ or $\text{Cov}_2(\tau, \tau, \delta)$ (these two quantities given by (20) and (21)) depending on how $\delta$ compares with $\tau$.

From these two quantities we can define a lead-lag correlation between the two stocks for $(\tau, \delta) \in \mathbb{R}_+ \times \mathbb{R}$ as:

$$C(\tau, \delta) = \begin{cases} \frac{L_{2\rightarrow 1}(\tau, \delta)}{\sqrt{C_1(\tau)C_2(\tau)}} & \text{if } \delta > 0, \\ \frac{L_{1\rightarrow 2}(\tau, -\delta)}{\sqrt{C_1(\tau)C_2(\tau)}} & \text{if } \delta < 0. \end{cases}$$

An illustration of the lagged correlation is given in Figure 2.

Suppose that $x > 0$ and $y = 0$ then an up jump of the second asset will induce an increase of $\lambda_t^{1,u}$ which increases the probability of an up jump of the first asset that will occur, if it occurs, with a delay. As a result, the function $\delta \rightarrow C(\tau, \delta)$ should be increasing at the vicinity of $0_+$. Conversely, if $x = 0$ and $y > 0$ then an up move of the first asset will imply an increase of $\lambda_t^{2,u}$ which increases the probability of an up jump of the second asset that will occur, if it occurs, with a delay. In that case the function $\delta \rightarrow C(\tau, \delta)$ will be decreasing at $0_-$. Clearly, the function $\delta \rightarrow C(\tau, \delta)$ should converge to zero for $|\delta|$ large and we expect a humped shape. If the effect provoked by $x$ dominates then the maximum of $\delta \rightarrow C(\tau, \delta)$ should be for $\delta > 0$, and in that case the second asset leads the first one, whereas if the $y$ effect dominates we expect the opposite, that is to say, a maximum for $\delta$ negative and in that case the first asset is the leader. Lastly, the two effects can cancel each other and it leads to a centred function, none of the assets leads the other.

3.3 The diffusive limit behaviour

In the previous section the dynamic is supposed to modelise the stock price evolution at high-frequency. At low frequency, typically daily, the usual framework is the one based on continuous diffusion processes driven by a Brownian motion. Recently, some works tried to fill the gap between these two time scales and these results are of interest because it enables the development of a micro foundation of daily quantities (the most well known being the Black-Scholes volatility). Along these lines let us mention, without pretending to be exhaustive, the works of Abergel and Jedidi (2013a), Cont and De Larrard (2011), Cont and De Larrard (2012) and Kirilenko et al. (2013). For the models based
on the Hawkes process most of the results, if not all, were systematically developed in Bacry et al. (2013a), Bacry et al. (2013b) and Bacry and Muzy (2013). We follow these authors and focus on the diffusive limit associated with the model proposed here with the aim of underlining the impact of the parameters on the quantities driving the stock at low frequency.

In order to compute the diffusive limit of the model we use the important Corollary 1 of Bacry et al. (2013b) which gives a central limit theorem:

**Proposition 12** Let \( N_t \) the four-dimensional Hawkes process then for \( t \in [0; 1] \)

\[
\frac{N_{nt}}{\sqrt{n}} - \sqrt{nt} \lambda_{\infty}
\]

converge in law for the Skorohod topology to

\[
(\beta - \alpha)^{-1} \beta \Sigma^{1/2} W_t
\]

with \( \{W_t; t \geq 0\} \) a four-dimensional Brownian motion and \( \Sigma \) the diagonal matrix with the \( i^{th} \) element given by \( ((\beta - \alpha)^{-1} \beta \lambda_{\infty})_i \).

Let us then write unit-time price increments for the first asset as similar results apply to the second asset:

\[
\eta_t^1 = \left[ (N_t^{1,u} - N_{t-1}^{1,u}) - (N_t^{1,d} - N_{t-1}^{1,d}) \right] \times \frac{\nu_1}{2},
\]

and consider the random sums

\[
S_n^1 = \sum_{i=1}^{n} \eta_t^1.
\]

Denote by

\[
\tilde{S}^1_{nt} = \frac{S^n_{[nt]}}{\sqrt{n}},
\]

and let \( \tilde{S}^n_t = (\tilde{S}^{1,n}_t, \tilde{S}^{2,n}_t)^\top \) the vector of the two stocks. Thanks to Proposition 12 we obtain the diffusive limit for the stocks as we have:

**Proposition 13** The vector \( \tilde{S}^n_t \) converges in law to the vector \( \tilde{S}_t = (\tilde{S}^1_t, \tilde{S}^2_t)^\top \) whose dynamic is given by:

\[
d\tilde{S}^1_t = \frac{\nu_1}{2} \sum_{j=1}^{4} (m_{1j} - m_{2j}) dW^j_t,
\]

\[
d\tilde{S}^2_t = \frac{\nu_2}{2} \sum_{j=1}^{4} (m_{3j} - m_{4j}) dW^j_t
\]

with \( m \) the matrix appearing in equation (40).
The stock price increments follow a Gaussian distribution, in the literature this model is usually referred to as the Bachelier model. From this result we deduce the covariance matrix of the assets:

**Proposition 14** Let the $2 \times 2$ covariance matrix of the assets such that:

$$
\sigma \sigma^T = \begin{pmatrix}
\sigma_{11} & \sigma_{12} \\
\sigma_{12} & \sigma_{22}
\end{pmatrix}
$$

then we have:

$$
\sigma_{11}^2 = \frac{\nu_1^2}{4} \sum_{j=1}^{4} (m_{1j} - m_{2j})^2, \tag{41}
$$

$$
\sigma_{12} = \frac{\nu_1 \nu_2}{4} \sum_{j=1}^{4} (m_{1j} - m_{2j})(m_{3j} - m_{4j}), \tag{42}
$$

$$
\sigma_{22}^2 = \frac{\nu_2^2}{4} \sum_{j=1}^{4} (m_{3j} - m_{4j})^2 \tag{43}
$$

that are explicitly given by

$$
\sigma_{11}^2 = \frac{\nu_1^2}{4} 2\lambda_{1,\infty}(\beta_1^2 x^2 y + \beta_2^2\gamma_2^2) + \lambda_{2,\infty}\beta_2(x\beta_1^2\gamma_2^2) (\gamma_2 - xy)^2(\gamma_1\gamma_2 - xy), \tag{44}
$$

$$
\sigma_{12} = \frac{\nu_1 \nu_2}{4} 2\beta_1 y \lambda_{1,\infty}(\beta_1^2 x\gamma_1 + \beta_2^2\gamma_2) + 2\beta_2 x \lambda_{2,\infty}(\beta_1^2 y\gamma_2 + \beta_2^2\gamma_1) (\gamma_1\gamma_2 - xy)^2(\gamma_1\gamma_2 - xy), \tag{45}
$$

$$
\sigma_{22}^2 = \frac{\nu_2^2}{4} 2\lambda_{2,\infty}(\beta_2^2 y^2 x + \beta_2^2\gamma_1) + \lambda_{1,\infty}\beta_2 y (\beta_1^2 y\gamma_2 + \beta_2^2\gamma_1) (\gamma_1\gamma_2 - xy)< (\gamma_1\gamma_2 - xy)^2(\gamma_1\gamma_2 - xy), \tag{46}
$$

with $\gamma_i = \beta_i + \alpha_{m} - \alpha_{s}^i$ and $\theta_i = \beta_i - \alpha_{m}^i - \alpha_{s}^i$ $\ i \in \{1, 2\}$.

**Remark 15** Note that when $x = y = 0$ then $\sigma_{12} = 0$ and $\sigma_{11}^2 = \frac{\nu_1^2}{4} \lambda_{1,\infty}$ as in Bacry et al. (2013a) if $\alpha_{s}^1 = 0$, or in Da Fonseca and Zaatour (2013a) if $\alpha_{m}^1 = 0$, or Da Fonseca and Zaatour (2013b) if $\alpha_{s}^1 \neq 0$ and $\alpha_{m}^1 \neq 0$.

**Remark 16** From Proposition 9 we can retrieve the diffusive limit for the volatility by considering the limit $\lim_{\tau \to +\infty} C(\tau)$ in equation (34), it leads to the computation of $\lim_{\tau \to +\infty} \beta\text{Cov}(\tau)$ with $\text{Cov}(\tau)$ given by equation (18). Taking into account the form of $c_5(\tau)$ this limit is given by:

$$
\lim_{\tau \to +\infty} \frac{1}{\tau}\text{Cov}(\tau) = \tilde{J}_1 + \tilde{J}_1^\top + \text{diag}(\tilde{\lambda}_{\infty}) \tag{47}
$$

with $\tilde{J}_1 = -(\alpha - \beta)^{-1}(\bar{\Lambda}_{\infty} + \alpha\text{diag}(\bar{\lambda}_{\infty}))$.

Similar remark applies to the covariance between the stocks given in Proposition 10, considering $\lim_{\tau \to +\infty} \text{CovS}(\tau)$ leads to the same limit equation.
Remark 17 Taking the limit with respect to $\tau$ in (37) and (38) gives
$$\lim_{\tau \to +\infty} L_{1,2}(\tau, \delta) = \lim_{\tau \to +\infty} L_{2,1}(\tau, \delta) = 0.$$ Hence, we cannot extract lead-lag relationship in the diffusive case or equivalently at low frequency (i.e., daily) a fact already underlined by Huth and Abergel (2012) and Bacry et al. (2013b). Note that this “flaw” is specific to our model and/or our approach. In Hoffmann et al. (2013) a Bachelier model that allows for lead-lag relationship is proposed but the modelling strategy is completely different from ours.

From equation (45) we conclude that if $x = y = 0$ then $\sigma_{12} = 0$ which is as expected. Due to sign constraints on the parameters if $x > 0$ and/or $y > 0$ we also conclude that $\sigma_{12} > 0$ which is also consistent with the dynamic for the stocks. If in the matrix $\alpha$ of (28) the upper-right matrix is given by (30) and lower-left matrix is given by (31) then the volatilities $\sigma_{11}^2$ and $\sigma_{22}^2$ will still be given by (44) and (46) whilst the covariance $\sigma_{12}$ will be minus the term (45). Hence, a negative correlation is achieved and it is consistent with the dynamic in that case.

3.4 Expansion with respect to coupling parameters

In order to gain some intuition on the impact of the model parameters we perform (first order) Taylor expansions of the computed quantities. As we are primarily interested in the interaction between the two stocks the expansion will be the done with respect to $x$ and $y$, that we qualify as coupling or lead-lag parameters. We first focus on the impact of the coupling parameters on the signature plot of the assets, the following proposition, which proof is postponed to the Appendix, explains the dependency with respect to these parameters:

**Proposition 18** Given the signature plot for the first asset of Proposition 9 then we have the following first order Taylor expansion:

$$C_1(\tau) = C_0(\tau) + xC_x(\tau) + yC_y(\tau)$$ (48)

where:

$$C_0(\tau) = \frac{\nu_1^2}{2} \Lambda_1 \left( \kappa_1^2 + \left( 1 - \kappa_1^2 \right) \frac{1 - e^{-\gamma_1 \tau}}{\gamma_1 \tau} \right),$$

$$C_x(\tau) = \frac{\nu_2^2}{2} \Lambda_2 \left( \kappa_1^2 + \left( 1 - \kappa_1^2 \right) \frac{1 - e^{-\gamma_1 \tau}}{\gamma_1 \tau} \right),$$

$$C_y(\tau) = 0$$
and

\[ \Lambda_i = \frac{\bar{\beta}_i \lambda_{i,\infty}}{\theta_i}, \quad \kappa_i = \frac{\bar{\beta}_i}{\gamma_i}, \]  

(49)

with \( \theta_i \) and \( \gamma_i \) defined for \( i \in \{1, 2\} \) were previously defined. Similar expression can be obtained for the second stock.

The expression of \( C_0(\tau) \) appears in [Bacry et al. (2013a)] with the parameters computed under the hypothesis \( \alpha_s^1 = 0 \), or in [Da Fonseca and Zaatour (2013a)] with the parameters computed under the hypothesis \( \alpha_m^1 = 0 \), or in [Da Fonseca and Zaatour (2013b)] with \( \alpha_s^1 \neq 0 \) and \( \alpha_m^1 \neq 0 \). Note that \( C_y(\tau) = 0 \).

Of importance is the fact that the functions \( \tau \rightarrow C_0(\tau) \) and \( \tau \rightarrow C_x(\tau) \) have the same shape which implies that the coupling parameter does not alter the shape of the signature plot. It will be decreasing in the purely mutually excited case, i.e. \( \alpha_s^1 = 0 \) as in [Bacry et al. (2013a)], or increasing as in [Da Fonseca and Zaatour (2013a)], or could be even flat if \( \alpha_s^1 = \alpha_m^1 \).

Having computed the expansion of the signature plot similar computations (we omit the proof) give the expression for the expansion of the covariance. We have:

**Proposition 19** The covariance between two stocks of equation (36) has the Taylor expansion:

\[ \text{Cov}(\tau) = \frac{\nu_1 \nu_2}{4} (\text{Cov}_0(\tau) + x\text{Cov}_x(\tau) + y\text{Cov}_y(\tau)) \]  

(50)

where:

\[ \text{Cov}_0(\tau) = 0 \]

\[ \text{Cov}_x(\tau) = \frac{2\Lambda_2}{\tau \gamma_1^2 \gamma_2^2 (\gamma_1 + \gamma_2)} \left( (\alpha_m^2 - \alpha_s^2)(\bar{\beta}_2 + \gamma_2)\gamma_1^2 - (1 - \tau \gamma_1)\bar{\beta}_2^2 \gamma_2 (\gamma_1 + \gamma_2) \right) \]

\[ + \frac{\Lambda_2}{\tau \gamma_1^2 \gamma_2 (\gamma_1 + \gamma_2)} \left( 2\gamma_1 \gamma_2 + 2\bar{\beta}_2 \gamma_2 + (\alpha_m^2 - \alpha_s^2)^2 \right) e^{-\gamma_1 \tau} \]

\[ - \frac{\Lambda_2 (\bar{\beta}_2 + \gamma_2)(\alpha_m^2 - \alpha_s^2)}{\tau \gamma_1^2 \gamma_2^2 (\gamma_1 + \gamma_2)} \left( \gamma_2^2 + 2\gamma_1 (\gamma_1 + \gamma_2) + \tau \gamma_2^2 (\gamma_1 + \gamma_2) \right) e^{-\gamma_2 \tau} \]

\[ \text{Cov}_y(\tau) = \frac{2\Lambda_1}{\tau \gamma_1^2 \gamma_2^2 (\gamma_1 + \gamma_2)} \left( (\alpha_m^1 - \alpha_s^1)(\bar{\beta}_1 + \gamma_1)\gamma_2^2 - (1 - \tau \gamma_2)\bar{\beta}_1^2 \gamma_1 (\gamma_1 + \gamma_2) \right) \]

\[ + \frac{\Lambda_1}{\tau \gamma_1 \gamma_2^2 (\gamma_1 + \gamma_2)} \left( 2\gamma_1 \gamma_2 + 2\bar{\beta}_1 \gamma_1 + (\alpha_m^1 - \alpha_s^1)^2 \right) e^{-\gamma_1 \tau} \]

\[ - \frac{\Lambda_1 (\bar{\beta}_1 + \gamma_1)(\alpha_m^1 - \alpha_s^1)}{\tau \gamma_1^2 \gamma_2 (\gamma_1 + \gamma_2)} \left( \gamma_1^2 + 2\gamma_2 (\gamma_1 + \gamma_2) + \tau \gamma_1^2 (\gamma_1 + \gamma_2) \right) e^{-\gamma_2 \tau}. \]
Remark 20 It is of interest to expand the lead-lag relation given by Proposition [11] but it leads to equations far too large.

Lastly, the expansion of the diffusive limit volatility is given by:

**Proposition 21** The first order Taylor expansion (with respect to \( a \) and \( y \)) of the diffusive limit \( \sigma_{11}^2 \), \( \sigma_{22}^2 \) and the correlation associated with the matrix of Proposition [14] is given by:

\[
\begin{align*}
\sigma_{11}^2 &= \frac{\nu_1^2}{4} \left( 2\kappa_1^2 \Lambda_1 + \frac{2\kappa_1^2}{\theta_1} \Lambda_2 x \right) \\
\sigma_{22}^2 &= \frac{\nu_2^2}{4} \left( 2\kappa_2^2 \Lambda_2 + \frac{2\kappa_2^2}{\theta_2} \Lambda_1 y \right) \\
\rho &= \frac{\sigma_{12}}{\sigma_{11} \sigma_{22}} = \frac{\kappa_1}{\kappa_2} \sqrt{\frac{\Lambda_1}{\Lambda_2}} \frac{y}{\gamma_2} + \frac{\kappa_2}{\kappa_1} \sqrt{\frac{\Lambda_2}{\Lambda_1}} \frac{x}{\gamma_1}
\end{align*}
\]

We note that an increase of \( x \) increases both \( \sigma_{11} \) and \( \rho \) and similar conclusion applies to \( y \).

4 Empirical Analysis

4.1 Data description and estimation methodology

We rely on tick-by-tick data from TRTH (Thomson Reuters Tick History)\(^3\). We deal with futures on indices such as Dax and Eurostoxx (respectively noted FDX and STXE in the tables), as well as some other stocks: Renault, Peugeot, Société Générale and BNP Paribas (respectively RENA.PA, PEUP.PA, SOGN.PA and BNPP.PA). The data covers the period between 2010/01/01 to 2011/12/31.

It consists of quote files recording quote changes (bid/ask prices and quantities) timestamped up to the millisecond, as well as trade files recording the transactions (prices and quantities) timestamped up to the millisecond. For every considered day, we took the front maturing future for the indices, i.e the future with nearest maturity, which is generally the most traded one. For every considered asset, we neglect the first and last 15 minutes in order to avoid the open and close auctions.

The estimation algorithm relies on maximum likelihood method. From Proposition 7.2.III of Daley\(^4\) Part of the data are provided by SIRCA http://www.sirca.org.au/.
and Jones (2002), the log-likelihood of a point process \((N_t)_{t \geq 0}\) writes up to an additive constant:

\[
L = -\int_0^T \lambda_t dN_t + \int_0^T \ln (\lambda_t) dN_t \\
= -\int_0^T \left( \lambda_\infty + \int_0^t e^{-\beta(t-s)} \alpha dN_s \right) \lambda_t \, dt + \sum_{i=1}^n \sum_{j=1}^{N_t} \ln (\lambda_t^i)
\]

So that, the log-likelihood of the multidimensional Hawkes process is the sum of the log-likelihoods generated by the observation of each coordinate process:

\[
L = \sum_{m=1}^n L_m.
\]

This takes a particularly simple form if we consider a diagonal structure for the \(\beta\) matrix, that is \(\beta = \text{diag}(\bar{\beta}_1, \ldots, \bar{\beta}_n)\), we obtain thanks to Ogata (1981):

\[
L_m = -\lambda_m^\infty T - \sum_{i=1}^n \sum_{j=1}^N \frac{\alpha_{mi}}{\beta_i} \left( 1 - e^{\tilde{\beta}_i (T-t_j)} \right) + \sum_{i=1}^{N_T} \ln \left( \lambda_m^\infty + \sum_{j=1}^{N_T} \alpha_{mi} R^{mi}(j) \right),
\]

where:

\[
R^{mi}(1) = 0, \\
R^{mm}(j) = e^{-\bar{\beta}_m (t_m^j - t_m^{j-1})} \left( 1 + R^{mm}(j-1) \right), \\
R^{mi}(j) = e^{-\bar{\beta}_i (t_m^i - t_m^{j-1})} R_m^{mi}(j-1) + \sum_{k: t_m^i \leq t_k^m < t_m^j} e^{-\bar{\beta}_i (t_m^i - t_k^m)} \text{ for } i \neq m.
\]

These recursive equations enable a very efficient calculation of the likelihood function.

We estimate the model as described in (28). The calibration strategy consists in beginning by calibrating the two Hawkes processes characterising each stock alone. This gives rise to two calibration problems with 4 parameters each, namely \(\lambda^i_\infty, \alpha^i_s, \alpha^i_s, \bar{\beta}^i\) where first guesses of \(\lambda^i_\infty, \alpha^i_s, \alpha^i_s\) are taken to be fractions of the Poisson lambda of the observed process (we take one tenth) , and \(\bar{\beta}^i\) is taken so as to ensure the stability condition. Once this calibration is solved, we turn to the entire problem, which has 10 parameters. First guesses for the \(\beta^i\) are taken to be the formerly found ones in the preceding

\[\text{Note that an even more efficient (in terms of computational speed) estimation algorithm can be developed using the moments and the autocorrelation function, see Da Fonseca and Zaatour (2013a) for an example, but it is not the purpose of this paper to focus on calibration speed.}\]
calibration. First guesses for the other parameters are half of the first parameters, so as to let some room for the new exciting parameters x and y to excite the process. First guesses for x and y are taken to be equal to the mean of all $\alpha$’s. For MLE maximisations, we rely on the Nelder Mead algorithm as implemented in the open source library NL-opt\(^5\). Notice that at every optimisation step, we check the stability condition of the process as specified in (32) and (33).

4.2 Estimation results

Results are gathered in Table 1. The table gives means, median and standard deviations of the parameters of the process, calibrated daily to the data.

[Insert Table 1 here]

In order to read the table, and in accordance with our previous notations, notice that for every pair (A,B), the value of $x$ carries the influence of B on A, and the value of $y$ carries the influence of A on B.

We are naturally primarily interested in the coupling parameters $x$ and $y$. We give them a closer look by plotting the time series of these pairs. In Figure 3, one can see that for the pair (SOGN.PA,BNPP.PA), $x$ and $y$ take heterogeneous values. There are some periods where the one clearly dominates the other, and some other periods where these values are not so far. The leader and lagger roles in this pair of large French banks seem to change their role from period to period.

As for the pair formed by the (STXE, BNPP.PA), different roles are well determined. The future on the index clearly leads the stock.

[Insert Figure 3 here]

In Figure 4, one can see that for the pair of stocks (RENA.PA, PEUP.PA), things are not as for the pair of banks. In fact, $x$ clearly dominates $y$, and then Peugeot seems to influence Renault more than the inverse. This can be explained by two facts: first, Peugeot stock is cheaper than Renault (average price in the considered period: 24 Euro for Peugeot versus 35 Euro for Renault). Therefore, bets on the automotive industry will be taken preferably in Peugeot rather than Renault, as Peugeot

\(^5\)http://ab-initio.mit.edu/wiki/index.php/NLopt
will ensure a better leverage. The French state being one of the principal stock holders in Renault it suggests that automotive industry speculators are likely to focus on Peugeot in the first place.

And finally, the Eurostoxx, the index of Euro zone stocks, naturally leads the DAX German index.

These lead-lag relationships can also be expressed in terms of time. Indeed, we have seen in Figure 2 that the correlation induced by a Hawkes framework, when \( x \) and \( y \) are different, reaches its maximum value when returns are calculated during two (overlapping) periods with a certain lag. This lag can be used to characterise the lead relationship. Indeed, for a pair \((A,B)\), if \( x > y \), and then \( B \) influences \( A \), the maximum correlation is achieved with a positive lag, and vice versa. Once our models are calibrated, we can calculate this optimal lag daily, which gives the Table 2.

5 Conclusion

In this paper we develop a multi-asset model using Hawkes process in the spirit of [Bacry et al., 2013a]. Within that framework we compute various statistical properties such as the signature plot, the covariance and the lagged covariance between the stocks. It allows us to precisely analyse the lead-lag relationship between the stocks, this is an important quantity that was, and still is, well studied within other frameworks (e.g., [de Jong and Nijman, 1997]). We perform some Taylor expansions for these quantities in order to gain a better understanding of the impact of the parameters on these key quantities. We also compute the diffusive limit associated with the model thereby connecting the parameters driving the high-frequency dynamic with the low frequency (i.e., daily) evolution of the stocks. We find that it is not possible to capture this lead-lag relationship at low frequency, a result that confirms previous works (e.g., [Huth and Abergel, 2012]).

We estimate the model using a two-year sample of high-frequency data for two index futures and four major stocks quoted on the Eurex market. We find that the Eurostoxx leads all the stocks which is a somewhat expected result as it is the largest European index. For the same reasons we find that the Eurostoxx also leads the DAX. For the two stocks in the banking sector when averaged over all the
sample none of them clearly leads the other. However, when the lead-lag relationship is analysed at a daily frequency we find some periods during which one stock clearly leads the other. For the two stocks of the automotive industry one of the stock systematically leads the other and it is consistent with the shareholder structure of these companies (one of them is partially state owned). Overall, the results are consistent with financial intuition.

Our work suggest several extensions. The same framework can be used to analyse the interactions between orders of different type (i.e., cancellation, amend, market and limit orders) for a given stock. It will provide us with a better understanding of the micro foundation of the stock price dynamic and the diffusive limit results would allow to quantify the contribution of these orders to the daily volatility. It would complete the existing works on that subject (e.g., Hautsch and Huang (2012), Chiarella et al. (2009), Eisler et al. (2012) and Hall and Hautsch (2006)). The same framework could be used in conjunction with a modelling of the volume to define the stock price dynamic. It would require to extend the analytical results and specify how the volume is related to the jumps of the Hawkes process (supposed to represent an order). The objective would be to keep the results tractable so that the diffusive limit could be computed. Along these lines let us quote the works of Cont and De Larrard (2011) and Cont and De Larrard (2012). Lastly, putting these results into an optimal order execution perspective is certainly challenging but definitively of interest.
References


Tables
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Note: Mean, median and standard deviation of calibration results for the different pairs.
Table 2: Lead Times

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Note. Mean, median and standard deviation of lead times. A negative value $t$ indicates that maximum correlation between the components of the pair is attained if we measure the increments of the second pair component $t$ seconds after those of the first component.
Figure 1: Illustration of the Epps effect reconstruction. We considered perfectly symmetric stocks, with $\alpha_s = \alpha_m = 0.004$ and considered two values for the coupling coefficients $x$ and $y$. Notice that when these latter are halved, the asymptotic correlation is always roughly halved. Notice also that the time taken to reach the asymptotic correlation does not depend on the coupling coefficients.

Figure 2: Illustration of the asymmetry of the correlation induced by a Hawkes process. We considered perfectly symmetric stocks, with $\alpha_1 = \alpha_2 = \alpha_3 = \alpha_m = 0.004$ and considered two values for the coupling coefficients $x$ and $y$. The figures report $\delta \to C(\tau, \delta)$ for $\delta \in \mathbb{R}$ with the function $C$ defined in Proposition 11 for two pairs of values for $(x, y)$; the first one is $(0.001, 0.01)$ and gives the blue-bullet curve, the second one is $(0.01, 0.001)$ and gives the red-triangle curve. In the right figure, a zoom around zero lag is performed to help to visualize the fact that maximum correlation is achieved for a certain lag.
Figure 3: We plot time series of the daily calibrated parameters $x$ (blue-bullet points) and $y$ (red-triangle points) for the pairs (SOGN.PA, BNPP.PA) on the left and (STXE,BNPP.PA) on the right, illustrating the evolution of the respective lead lag relationships in time. Notice that the index systematically leads the stock as is clear on the right figure. The relationship between Société Générale and BNP Paribas is more mitigated, even that beginning April 2011, the two stocks began a bearish period, where Société Générale is clearly the leader.

Figure 4: We plot time series of the daily calibrated parameters $x$ (blue-bullet points) and $y$ (red-triangle points) for the pairs (RENA.PA, PEUP.PA.PA) on the left and (STXE,FDX) on the right, illustrating the evolution of the respective lead lag relationships in time. The European index systematically leads the German index, while Peugeot systematically leads Renault, even if the feedback effect is here more pronounced than in the case of the indices.
Appendix

Proof of Lemma 1
Taking into account the fact that $dN_t - \lambda_t dt$ is a martingale we deduce (7). We rewrite the dynamic (1) as

$$d\lambda_t = \beta(\lambda_\infty - \lambda_t)dt + \alpha(dN_t - \lambda_t dt) + \alpha\lambda_t dt$$

and using again the martingale property of $dN_t - \lambda_t dt$ we deduce (6) after taking the expectation. ■

Proof of Lemma 3
Using mainly Chapter II section 6 of Protter (2004) we have:

$$d(N_tN_t^\top) = dN_tN_t^\top + N_tdN_t^\top + d[N_t, N_t^\top]_t$$

and $dN_tN_t^\top = (dN_t - \lambda_t dt)N_t^\top + \lambda_t N_t^\top dt$, $d[N_t, N_t^\top]_t = \text{diag}(\lambda_t)dt$ (the diagonal form is due to the fact that no simultaneous jumps can occur) combined with the martingale property of $dN_t - \lambda_t dt$ we deduce (14) after taking the expectation.

To obtain (15) we proceed as follows:

$$d(\lambda_t N_t^\top) = d\lambda_t N_t^\top + \lambda_t dN_t^\top + d[\lambda_t, N_t^\top]_t.$$  

As we have:

$$d\lambda_t N_t^\top = (\beta(\lambda_\infty - \lambda_t)dt + \alpha dN_t)N_t^\top = \beta(\lambda_\infty - \lambda_t)N_t^\top \text{dt} + \alpha(dN_t - \lambda_t dt)N_t^\top + \alpha\lambda_t N_t dt$$

and $\lambda_t dN_t^\top = \lambda_t(dN_t^\top - \lambda_t^\top dt) + \lambda_t^\top dt$ and $d[\lambda_t, N_t^\top]_t = \text{diag}(\lambda_t)dt$ we obtain the result.

To obtain (16) we proceed along the same lines using the fact that $d[\lambda_t, \lambda_t^\top]_t = \text{diag}(\lambda_t)\alpha^\top dt$. Direct integration gives the equations (6) and (10). ■

Proof of Lemma 4
We start with:

$$I_1 = E\left[(N_{t+\tau} - N_t)(N_{t+\tau} - N_t)^\top\right]$$

$$= E\left[N_{t+\tau}N_{t+\tau}^\top\right] - E\left[N_{t+\tau}N_t^\top\right] - E\left[N_tN_{t+\tau}^\top\right] + E\left[N_tN_t^\top\right]$$

$$= 2E\left[N_tN_t^\top\right] + \int_t^{t+\tau} E\left[\lambda_s N_s^\top\right] + E\left[N_s\lambda_s^\top\right] + \text{diag}(E[\lambda_s])ds - E\left[N_{t+\tau}N_t^\top\right] - E\left[N_tN_{t+\tau}^\top\right] (51)$$

where from (51) to (52) we used (14). Moreover, we have:

$$I_2 = \int_t^{t+\tau} E\left[\lambda_s N_s^\top\right] ds$$

$$= \int_t^{t+\tau} e^{(\alpha - \beta)(s-t)}E\left[\lambda_s N_s^\top\right] ds + \int_t^{t+\tau} \int_s^{t+\tau} e^{(\alpha - \beta)(s-u)} \left\{ \beta\lambda_\infty E\left[N_u^\top\right] + E\left[\lambda_u\lambda_u^\top\right] + \text{diag}(E[\lambda_u]) \right\} duds$$

$$= \int_t^{t+\tau} e^{(\alpha - \beta)(s-t)}E\left[\lambda_s N_s^\top\right] ds + \int_t^{t+\tau} \int_s^{t+\tau} e^{(\alpha - \beta)(s-u)} \left\{ \beta\lambda_\infty E\left[N_u^\top\right] + \beta\lambda_\infty \int_u^{t+\tau} E\left[\lambda_r^\top\right] dr \right\} duds$$

$$+ \int_t^{t+\tau} \int_s^{t+\tau} e^{(\alpha - \beta)(s-u)} \left\{ E\left[\lambda_u\lambda_u^\top\right] + \text{diag}(E[\lambda_u]) \right\} duds (53)$$

where we used successively (15) and (11). The fifth term of (52) is, after using the ODE for $E[N_t]$ and conveniently conditioning, equal to:

$$I_3 = E\left[N_{t+\tau}N_t^\top\right]$$

$$= E\left[ \left(N_t + \int_t^{t+\tau} (c_0(s-t)\lambda_s + c_1(s-t))ds \right) N_t^\top \right]. (55)$$

32
The first term of (55) will cancel with the first term of (52), the second term of (55) with will cancel with the first term of (54) whilst the last term of (55) with the second term of (52) when $t \to +\infty$. Therefore, for $t$ large we have

$$ I_1 = \int_t^{t+\tau} \int_t^s e^{(\alpha - \beta)(s-u)} \left\{ \beta \lambda_t \int_t^s \mathbb{E} \left[ \lambda_t^\top \right] dr + \mathbb{E} \left[ \lambda_u \lambda_u^\top \right] + \alpha \text{diag} (\mathbb{E} [\lambda_u]) \right\} dus $$

(56)

Replacing in $K_1$ the expectations involving $\lambda_t$ by their long term values we obtain:

$$ K_1 = c_4(\tau) \beta \lambda_\infty \lambda_\infty^\top + c_5(\tau) (\Lambda_\infty + \alpha \text{diag} (\lambda_\infty)) $$

(58)

$$ c_4(\tau) = - (\alpha - \beta)^{-1} \frac{\tau^2}{2} - (\alpha - \beta)^{-2} \tau + (\alpha - \beta)^{-3} \left( e^{(\alpha - \beta)\tau} - I \right) $$

(59)

$$ c_5(\tau) = - (\alpha - \beta)^{-1} \tau + (\alpha - \beta)^{-2} (e^{(\alpha - \beta)\tau} - I). $$

(60)

As $c_4(t)$ is related to $c_5(\tau)$ through:

$$ c_4(\tau) = \left( \frac{\tau^2}{2} - c_5(\tau) \right) (- (\alpha - \beta)^{-1}), $$

(61)

$K_1$ can be rewritten as:

$$ K_1 = \frac{\tau^2}{2} \lambda_\infty \lambda_\infty^\top + c_5(\tau) (\Lambda_\infty + \alpha \text{diag} (\lambda_\infty)). $$

Taking into account:

$$ \lim_{t \to \infty} \mathbb{E} [N_{t+\tau} - N_t] \mathbb{E} \left[ (N_{t+\tau} - N_t)^\top \right] = \tau^2 \lambda_\infty \lambda_\infty^\top $$

we deduce the result. ■

**Proof of Lemma 5**

We need to determine:

$$ I_4 = \mathbb{E} \left[ (N_{t_4} - N_{t_3})(N_{t_2} - N_{t_1})^\top \right] $$

$$ = \mathbb{E} \left[ \mathbb{E}_3 \left[ (N_{t_4} - N_{t_3})(N_{t_2} - N_{t_1})^\top \right] \right] $$

(62)

$$ = \mathbb{E} \left[ (c_2(\tau_2) \lambda_{t_2} + c_3(\tau_2))(N_{t_2} - N_{t_1})^\top \right] $$

(63)

$$ = c_2(\tau_2) c_3(\delta) \mathbb{E} \left[ \lambda_{t_2} (N_{t_2} - N_{t_1})^\top \right] + c_2(\tau_2) c_3(\delta) \mathbb{E} \left[ (N_{t_2} - N_{t_1})^\top \right] + c_3(\tau_2) r_{t_1} \lambda_\infty $$

(64)

where from (62) to (63) we used (10), and from (63) to (64) we used (9) as well as (13). Taking into account that:

$$ \mathbb{E} \left[ \lambda_{t_2} (N_{t_2} - N_{t_1})^\top \right] = \mathbb{E} \left[ \lambda_{t_2} N_{t_2}^\top \right] - \mathbb{E} \left[ \lambda_{t_2} N_{t_1}^\top \right] $$

$$ = e^{(\alpha - \beta)\tau_2} \mathbb{E} \left[ \lambda_{t_1} N_{t_2}^\top \right] + \int_{t_1}^{t_2} e^{(\alpha - \beta)(t_2-s)} \left\{ \beta \lambda_s \mathbb{E} \left[ N_s^\top \right] + \mathbb{E} \left[ \lambda_s \lambda_s^\top \right] + \alpha \text{diag} (\mathbb{E} [\lambda_s]) \right\} ds $$

$$ - \left( c_0(\tau_2) \mathbb{E} \left[ \lambda_{t_1} N_{t_1}^\top \right] + c_1(\tau_2) \mathbb{E} \left[ N_{t_1}^\top \right] \right). $$

The first term of the last equation simplifies with last-but-one term. Replacing $\mathbb{E} \left[ N_s^\top \right]$ by its integral given by (10) allows us to simply the last term of the equation and we are left with

$$ \mathbb{E} \left[ \lambda_{t_2} (N_{t_2} - N_{t_1})^\top \right] = \int_{t_1}^{t_2} e^{(\alpha - \beta)(t_2-s)} \left\{ \beta \lambda_s \mathbb{E} \left[ \lambda_s^\top \right] + \mathbb{E} \left[ \lambda_s \lambda_s^\top \right] + \alpha \text{diag} (\mathbb{E} [\lambda_s]) \right\} ds. $$

Taking the long term values for the expectations (involving only the process $\lambda_t$) we get:
\[ \mathbb{E} \left[ \lambda_{t_2} (N_{t_2} - N_{t_1})^T \right] = c_5(\tau_1) \beta \lambda_\infty \bar{\lambda}_\infty^\top + c_2(\tau_1) \left( \Lambda_\infty + \text{odiag}(\bar{\lambda}_\infty) \right). \] (65)

As \( c_5(\tau) \) is related to \( c_2(\tau) \) through:
\[ c_5(\tau) = (\tau - c_2(\tau)) \left( - (\alpha - \beta)^{-1} \right) \] (66)
when used in conjunction with (65) in (64) leads to, after taking into account (13) for the second term and the definition for \( \bar{\lambda}_\infty \) given by (11), to the following expression for \( I_4 \):
\[ I_4 = c_2(\tau_2) c_0(\delta) \left\{ \tau_1 \bar{\lambda}_\infty \bar{\lambda}_\infty^\top + c_2(\tau_1) \left( \bar{\Lambda}_\infty + \text{odiag}(\bar{\lambda}_\infty) \right) \right\}. \]

Taking into account the equalities \( c_3(\tau) = (\tau - c_2(\tau)) \bar{\lambda}_\infty \) and \( c_1(\delta) = (I - c_0(\delta)) \bar{\lambda}_\infty \) then if we subtract to \( I_4 \) the following quantity:
\[ \lim_{t_1 \to \infty} \mathbb{E} [N_{t_4} - N_{t_3}] \mathbb{E} [(N_{t_2} - N_{t_1})^T] = \tau_2 \tau_1 \bar{\lambda}_\infty \bar{\lambda}_\infty^\top \]
we obtain the result. \( \blacksquare \)

**Proof.** of Lemma 6

Under the hypothesis of the lemma we can decompose the expectation as:
\[ I_5 = \mathbb{E} [(N_{t_4} - N_{t_2})(N_{t_2} - N_{t_1})^T] \]
\[ = \mathbb{E} [(N_{t_4} - N_{t_2}) + (N_{t_2} - N_{t_1})] (N_{t_2} - N_{t_1})^T] \]
\[ = \mathbb{E} [(N_{t_4} - N_{t_2}) (N_{t_2} - N_{t_1})^T] + \mathbb{E} [(N_{t_2} - N_{t_3}) (N_{t_2} - N_{t_1})^T] \]
\[ = \mathbb{E} [(N_{t_4} - N_{t_2}) (N_{t_2} - N_{t_1})^T] + \mathbb{E} [(N_{t_2} - N_{t_3}) (N_{t_2} - N_{t_1})^T] \]
\[ + \mathbb{E} [(N_{t_2} - N_{t_3}) (N_{t_3} - N_{t_1})^T]. \]

Similarly, if we decompose the product \( \mathbb{E} [N_{t_4} - N_{t_3}] \mathbb{E} [(N_{t_2} - N_{t_1})^T] \) then using Lemma 5 we obtain the announced result. \( \blacksquare \)

**Proof.** of Proposition 14

The result is obtained by direct computation but we recommend the use of a symbolic calculator. The code leading to the results is available upon request. \( \blacksquare \)

**Proof.** of Proposition 18

To perform the expansion we need to differentiate the function (18). Let us define \( \alpha_x = \frac{dx}{dy} \), \( \alpha_y = \frac{dy}{dx} \), \( \alpha^0 = \alpha_{x=0,y=0} \).

Starting from \( I = \alpha^{-1} \alpha \) and taking into account the fact that \( \beta \) does not depend on \( x \) and \( y \) we deduce:
\[ (\alpha^{-1})_x = - \alpha^{-1} \alpha_x \alpha^{-1} \]
\[ ((\alpha - \beta)^{-1})_x = -(\alpha - \beta)^{-1} \alpha_x (\alpha - \beta)^{-1} \]

( these equations will be evaluated for \( \alpha = \alpha^0 \) ) and similarly:
\[ (\alpha^{-2})_x = - \alpha^{-2} (\alpha_x \alpha + \alpha_x \alpha^2) (\alpha^2)^{-1} \]
\[ = - \alpha^{-2} \alpha_x \alpha^{-1} - \alpha^{-1} \alpha_x \alpha^{-2}. \]

For example, from the previous equations we deduce that:
\[ ((\alpha - \beta)^{-2})_x = -(\alpha - \beta)^{-2} \alpha_x (\alpha - \beta)^{-1} - (\alpha - \beta)^{-1} \alpha_x (\alpha - \beta)^{-2}. \]

From the equation \( \bar{\lambda}_{\infty} = -(\alpha - \beta)^{-1} \beta \lambda_\infty \) we define:
\[ \bar{\lambda}_{\infty}^0 = -(\alpha^0 - \beta)^{-1} \beta \lambda_\infty \]
\[ \bar{\lambda}_{\infty}^{x=0} = \left( \frac{d \bar{\lambda}_{\infty}}{dx} \right)_{x=0} = ((\alpha^0 - \beta)^{-1} \alpha_x (\alpha^0 - \beta)^{-1}) \beta \lambda_\infty \]

34
The result is obtained by direct computation but we recommend the use of a symbolic calculator. The code leading to the results is available upon request.

Proof. of Proposition 19
The result is obtained by direct computation but we recommend the use of a symbolic calculator. The code leading to the results is available upon request.

Proof. of Proposition 21
The result is obtained by direct computation but we recommend the use of a symbolic calculator. The code leading to the results is available upon request.

with similar equation for \( \lambda_{y,\infty}^0 \). We expand \( \hat{\lambda}_{\infty} \) solution of:

\[
(\alpha - \beta)\hat{\lambda}_{\infty} + \hat{\lambda}_{\infty}(\alpha - \beta)^T + \alpha \text{diag}(\hat{\lambda}_{\infty})\alpha^T = 0
\]

in the form \( \hat{\lambda}_{\infty} = \hat{\lambda}_{\infty}^0 + x\hat{\lambda}_{\infty}^0 + y\hat{\lambda}_{y,\infty}^0 \) with:

\[
(\alpha^0 - \beta)\hat{\lambda}_{\infty} + \hat{\lambda}_{\infty}(\alpha^0 - \beta)^T + \alpha^0 \text{diag}(\hat{\lambda}_{\infty})\alpha^T = 0
\]

and

\[
(\alpha^0 - \beta)\hat{\lambda}_{y,\infty}^0 + \hat{\lambda}_{y,\infty}^0(\alpha^0 - \beta)^T = -\alpha_x\hat{\lambda}_{\infty}^0 - \hat{\lambda}_{\infty}^0\alpha_x^T - \alpha_x \text{diag}(\hat{\lambda}_{\infty}^0)\alpha^T + \alpha^0 \text{diag}(\hat{\lambda}_{\infty})\alpha^T
\]

with a similar equation for \( \bar{\lambda}_{y,\infty}^0 \).

We need to differentiate \( \text{Cov}(\tau) \) given by \([18]\) which leads to differentiate \( c_3(\tau) \) \([60]\). We denote \( c_3^0(\tau) \) the function evaluated for \( x = y = 0 \) and the derivative is just:

\[
\partial_x c_3(\tau)|_{x=y=0} = \partial_x c_3^0(\tau) = (\alpha^0 - \beta)^{-1}\alpha_x(\alpha^0 - \beta)^{-1}_x + \tau(\alpha^0 - \beta)^{-2}\alpha_x e^{(\alpha^0 - \beta)_x}
\]

Lastly, the expansion of \( J_1 \) is:

\[
J_1 = J_1^0 + xJ_{1,x}^0,
\]

\[
J_1^0 = c_3^0(\tau)(\hat{\lambda}_{\infty}^0 + \alpha \text{diag}(\hat{\lambda}_{\infty}^0)),
\]

\[
J_{1,x}^0 = \partial_x c_3^0(\tau)(\hat{\lambda}_{\infty}^0 + \alpha \text{diag}(\hat{\lambda}_{\infty}^0)) + c_3^0(\tau)(\hat{\lambda}_{\infty}^0 + \alpha \text{diag}(\hat{\lambda}_{\infty}^0)) + \alpha \text{diag}(\hat{\lambda}_{\infty}^0)).
\]

Therefore, we have the expansion for \( \text{Cov}(\tau) \) given by:

\[
\text{Cov}(\tau) = J_1^0 + (J_1^0)^T + \tau \text{diag}(\hat{\lambda}_{\infty}^0)
\]

\[
+ x \left( J_{1,x}^0 + (J_{1,x}^0)^T + \tau \text{diag}(\hat{\lambda}_{\infty,\infty}^0) \right) + y \left( J_{1,y}^0 + (J_{1,y}^0)^T + \tau \text{diag}(\hat{\lambda}_{y,\infty}^0) \right)
\]

from which we can deduce the expansion of the signature plot. It still requires tedious computation and we recommend the use of a symbolic calculator. The code leading to the results is available upon request.